



Handbook of Research on Design, Control, and Modeling of Swarm Robotics (Advances in Computational Intelligence and Robotics)

Ying Tan

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Studies on robotics applications have grown substantially in recent years, with swarm robotics being a relatively new area of research. Inspired by studies in swarm intelligence and robotics, swarm robotics facilitates interactions between robots as well as their interactions with the environment.

The **Handbook of Research on Design, Control, and Modeling of Swarm Robotics** is a collection of the most important research achievements in swarm robotics thus far, covering the growing areas of design, control, and modeling of swarm robotics. This handbook serves as an essential resource for researchers, engineers, graduates, and senior undergraduates with interests in swarm robotics and its applications.

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